

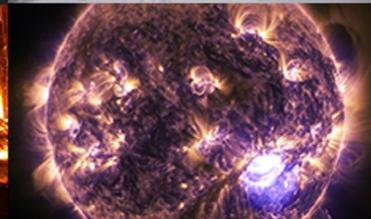
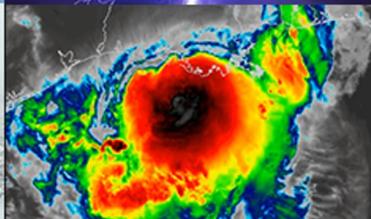
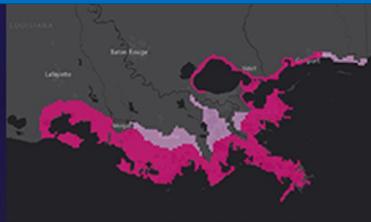
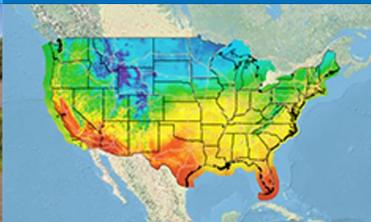
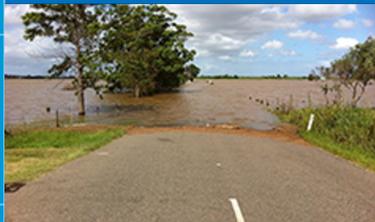


**NATIONAL  
WEATHER  
SERVICE**

# Data Assimilation – Introduction for Breakout Session

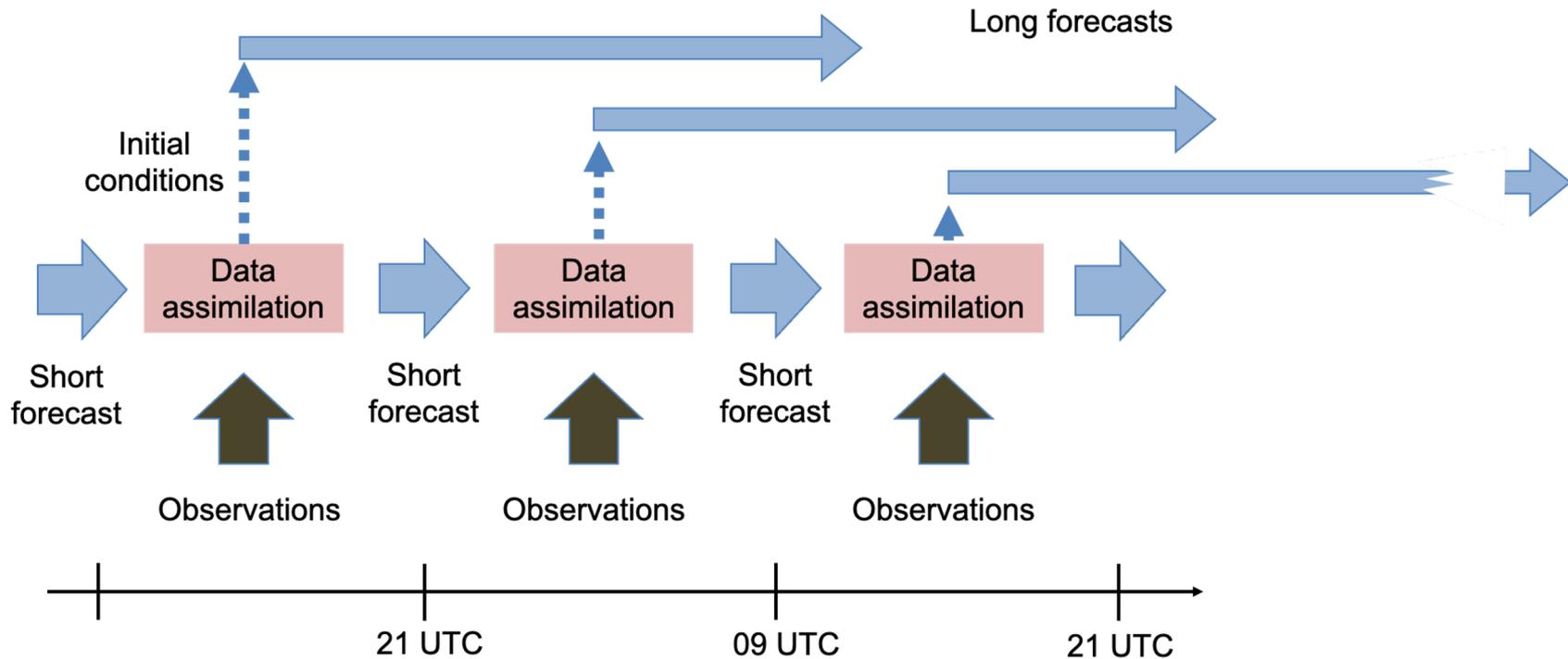
Daryl Kleist - Chief, Data Assimilation & Quality Control Group  
Environmental Modeling Center  
NOAA/NWS/NCEP

AI4NWP Workshop, 28-29 November 2023, Boulder, CO



# Data assimilation for numerical weather prediction: (NWP)

Blending short forecasts and new observational data in a statistically optimal way



From Alan Geer (ECWMF, Presentation at 2nd NOAA AI Workshop)

# Variational DA (adapted from Y. Tremolet)

Variational Data Assimilation is used by operational centers for NWP (GSI, NAVDAS, IFS, VAR, ...)

Principle: minimize the distance between the analysis and all available observations over the assimilation window. *Solved for iteratively.*

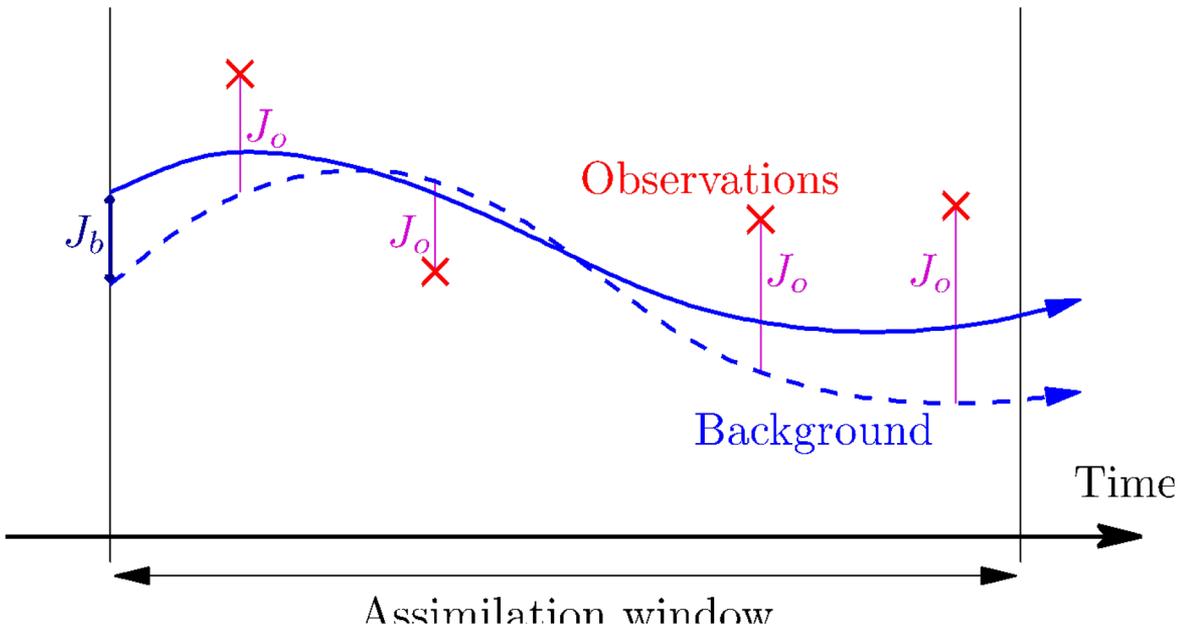
$\mathbf{x}_b$  Background state

$\mathbf{y}$  Observations

$\mathcal{H}$  Observation operator

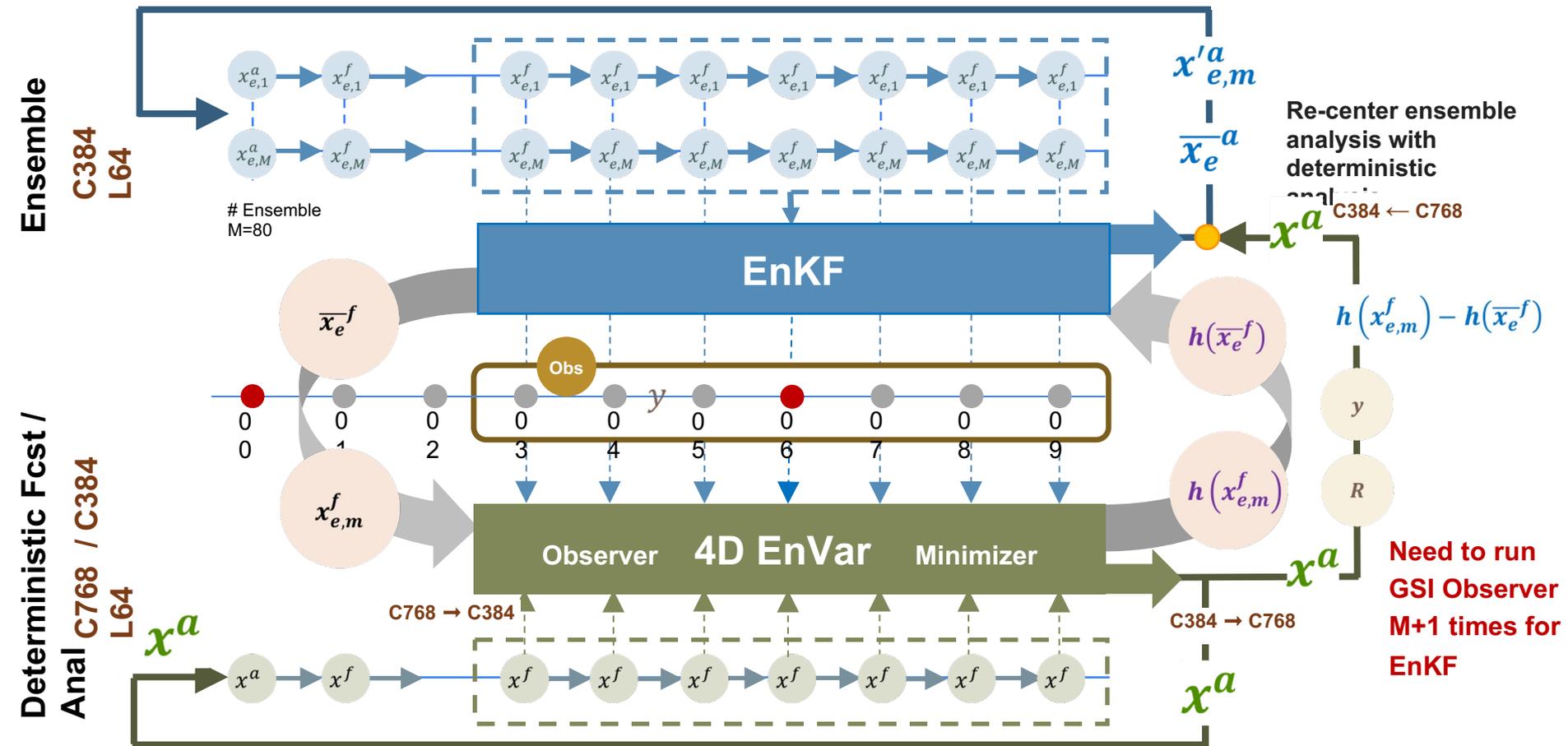
$\mathbf{B}$  Background error covariance

$\mathbf{R}$  Observation error covariance

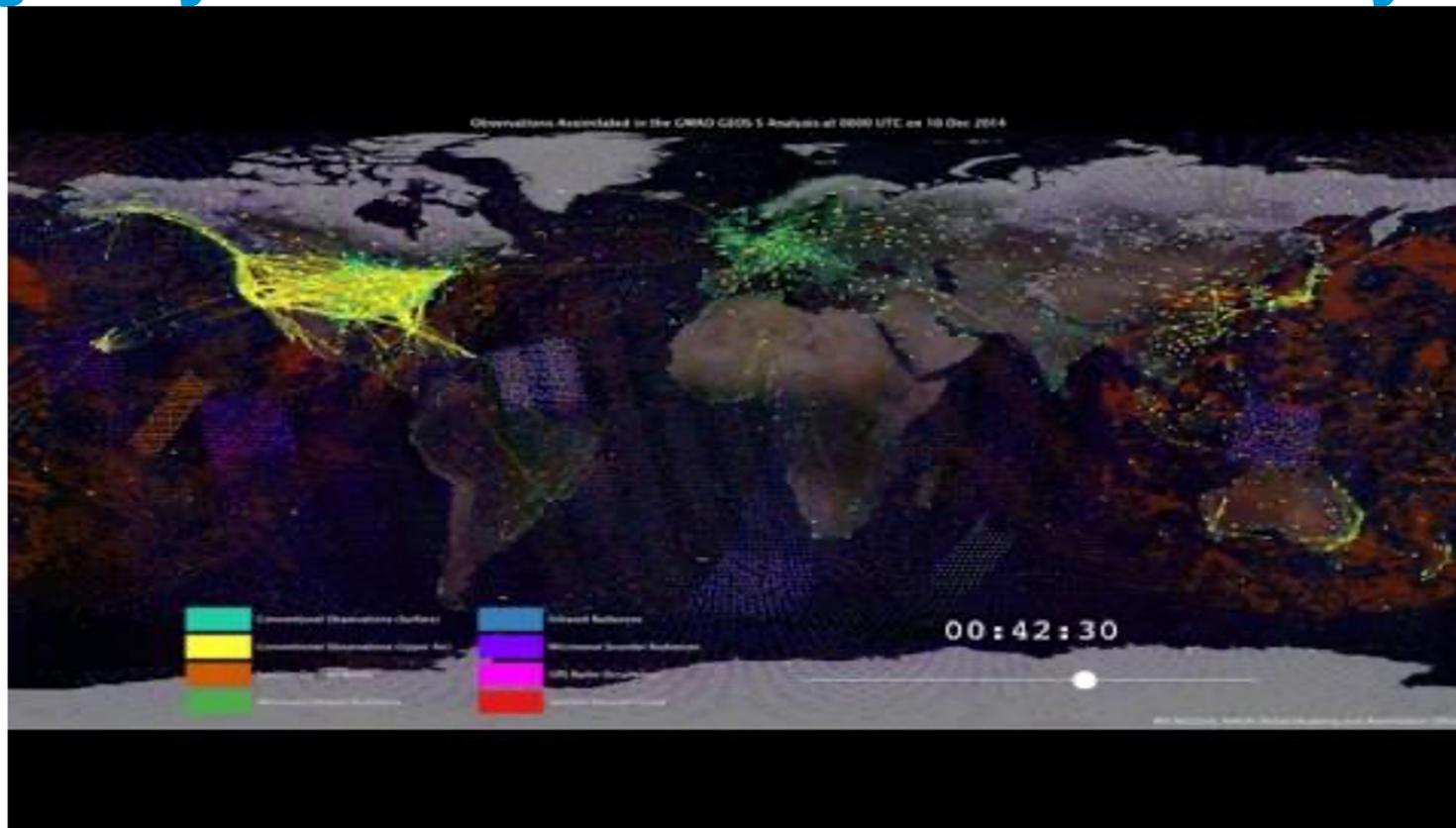


$$J(\mathbf{x}) = \frac{1}{2}(\mathbf{x} - \mathbf{x}_b)^T \mathbf{B}^{-1}(\mathbf{x} - \mathbf{x}_b) + \frac{1}{2}[\mathcal{H}(\mathbf{x}) - \mathbf{y}]^T \mathbf{R}^{-1}[\mathcal{H}(\mathbf{x}) - \mathbf{y}]$$

# Coupled Deterministic / Ensemble Systems (courtesy Emily Liu)

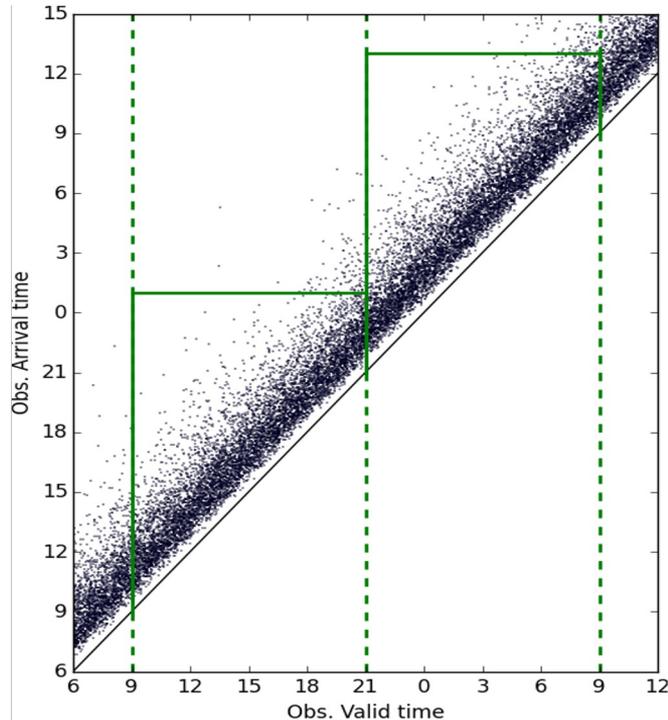


# Single Cycle Global Data Assimilation System



Example of observations assimilated into single six-hour GDAS updated. Animation courtesy of Will McCarty (NASA) – circa 2014

# Observations (from Y. Tremolet/JCSDA)



To perform analysis, observations are used within time window

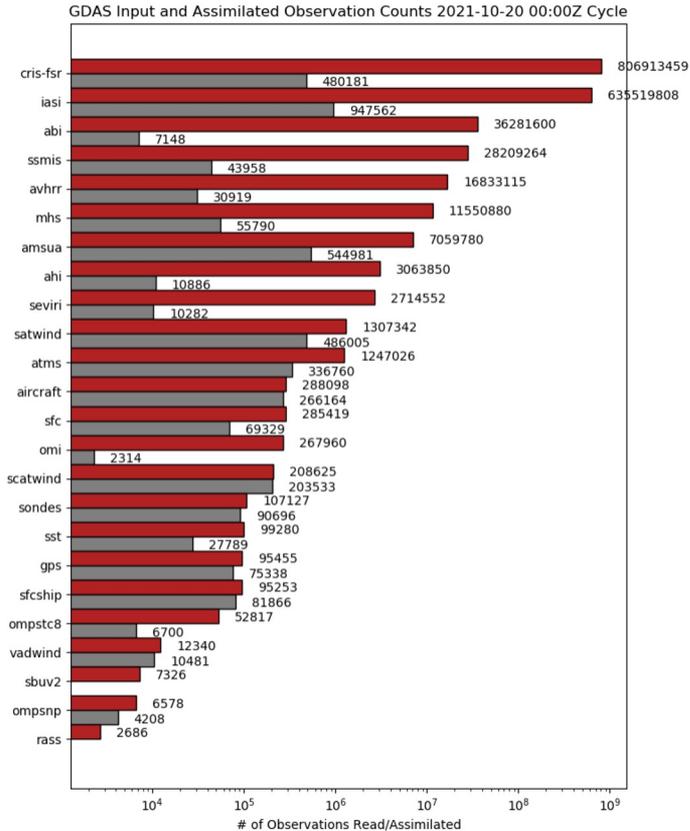
*Computational issue:* Observations do not instantaneously appear at operational centers:

- Communications delays
- Ground stations locations
- Pre-processing...

Some observations are lost

Some computational effort is lost

# Underutilized Observing System



- The current global observing system for NWP is diverse, robust and rapidly evolving
- We are still under-utilizing what we already have
  - Representativeness issues
  - Scientific challenges (e.g., all-sky/all-surface radiance assimilation)
  - Redundancy and risk reduction
  - Complexity / computational limitations
- Potential for use of AI/ML for data (including channel) selection, superobbing (maximizing information content), and quality control

From NCEP 10 Year Development Strategy (to be published Dec. 2023)

## ML for DA priorities

1. **Observations** – *quality control, data selection, bias correction, super-observations, extraction of maximal information content, anomaly detection and operational monitoring;*
2. **Forward operator emulation** – *computational efficiencies, replacement for complex operators;*
3. **Background error** – *computational efficiencies, multivariate aspects and coupled assimilation, parameter estimation for error models;*
4. **Background** – *dynamic downscaling, bias correction;*
5. **Model error** – *estimation and correction;*
6. **Emulator exploitation** – *replacement for TL/AD in 4DVar, efficient creation of huge ensembles to avoid localization.*

# Joint Effort for Data assimilation Integration (JEDI) Infrastructure for Unified Data Assimilation

**JEDI** is a project within the Joint Center for Satellite Data Assimilation (JCSDA)

JEDI provides a **software infrastructure for data assimilation** that

- is model agnostic
- is generic and portable, from toy models running on laptops to operational Earth system coupled models running in the cloud.
- enables DA on the model native grid
- does not impose one specific DA methodology or algorithm
- provides a framework for rapid uptake of new observations into operations with generic observation handling and modeling
- encourages implementation of model-independent observation operators
- provides a unified Interface for Observation Data Access (IODA)

***NOAA is committed to JEDI – and could be enabler for integration of ML to help with DA problems....***



**Or...**

**Do we even need DA?**

# Backup Slides

# Cost / loss function equivalence of ML and variational DA

Assume Gaussian errors (error standard deviation  $\sigma$ )  
and for clarity here simplify to scalar variables  
and ignore any covariance between observation, model or state error

ML

Loss function

Basic loss  
function

Feature  
error?

Weights  
regularisation

$$J(x, w) = \underbrace{\frac{(y - h(x, w))^2}{(\sigma^y)^2}}_{Jy} + \underbrace{\frac{(x^b - x)^2}{(\sigma^x)^2}}_{Jx} + \underbrace{\frac{(w^b - w)^2}{(\sigma^w)^2}}_{Jw}$$

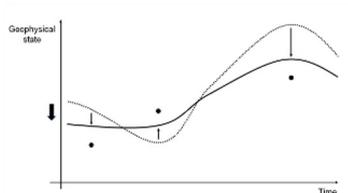
DA

Cost function

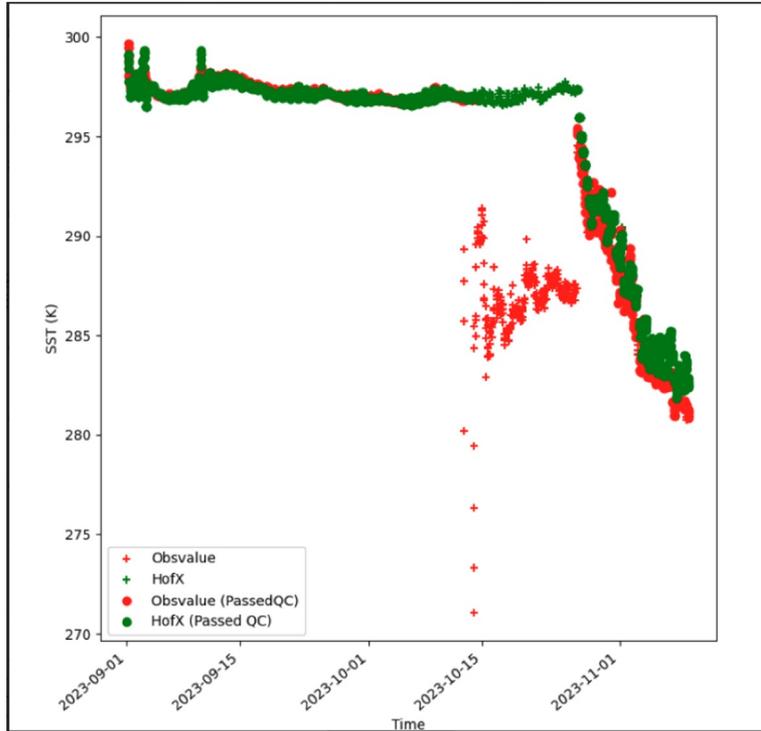
Observation term

Prior knowledge  
of state

Prior knowledge  
of model



# Dynamic Quality Control

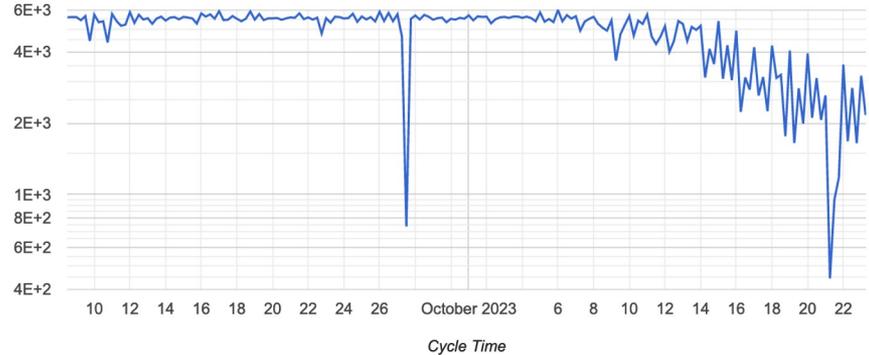


Example of buoy observation gone awry – Obs values (red), Hx (green) before (cross) or having passed QC (dots). In this case, the buoy went bad in such a way in early November that it was able to pass QC while getting worse, dragging the SST analysis with it.

## AMSUA\_METOP-C, Time Series Plot

Valid 2023102306

Number of Observations  
amsua\_metop-c, 2023102306



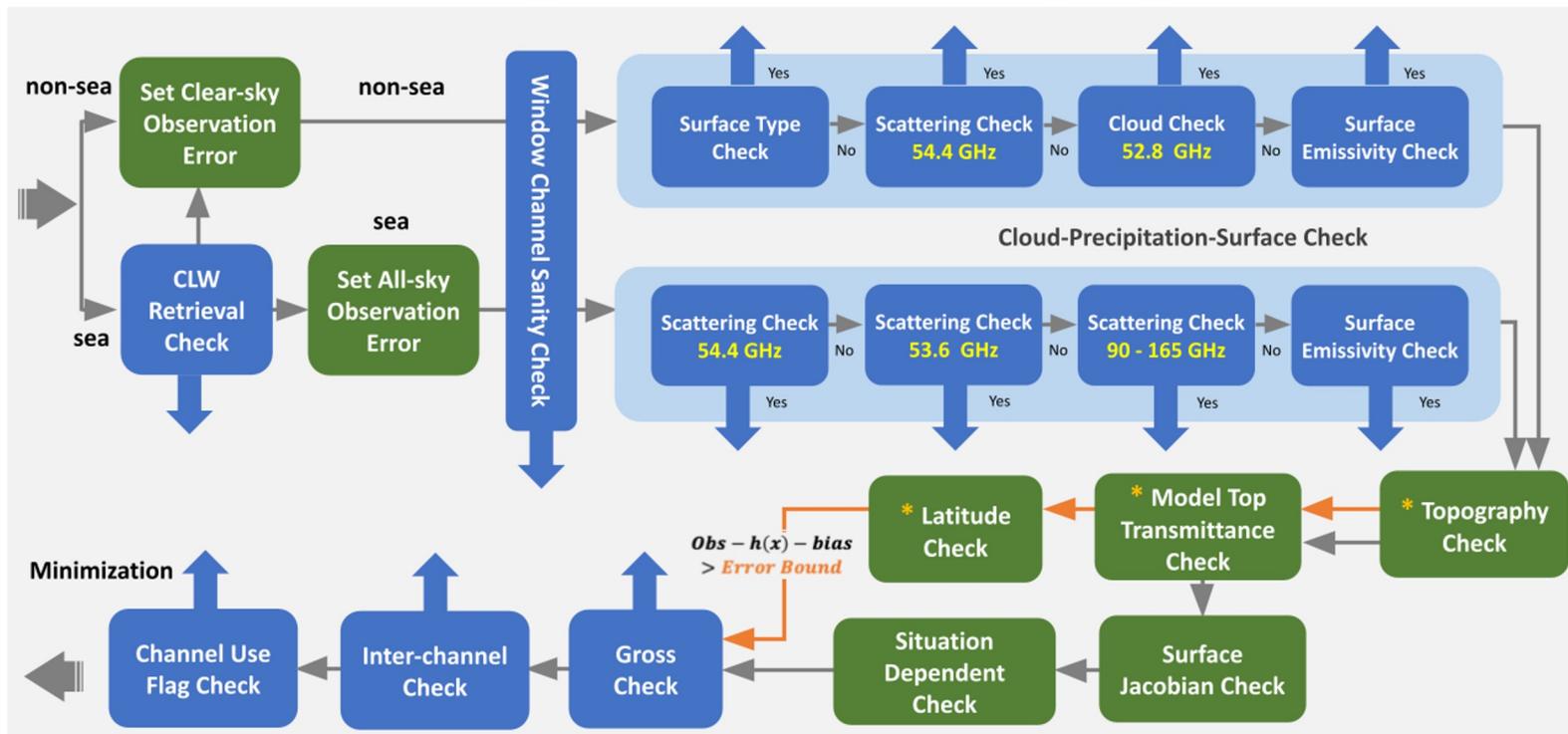
Time series of # observations accept for assimilation from a particular channel from amsu-a on metop-c. In this case, there was an encoding issue with a single channel that was causing erroneous quality control to throw out data.

# Quality control can be quite complex

## Quality Control Flowchart

## All-sky ATMS

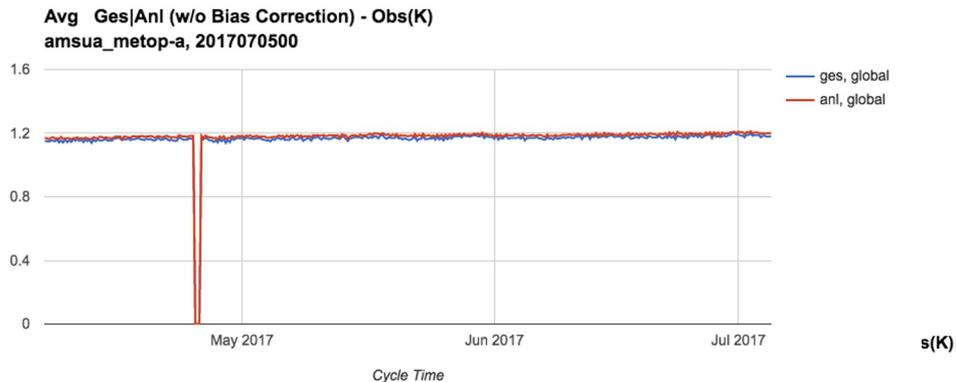
A process of observation **Screening**, **Error Inflation**, and **\*Error Bound Tightening** from their original values



# Bias Correction

- Many assumptions made to perform data assimilation problem – bias in observations (or simulated observations) and/or background violates some assumptions.
- Bias in simulated observation and observations themselves can come from many sources:
  - Inadequacies in characterization of instrument
  - Deficiencies in forward models (operators) - mapping model/background to observations space
  - Errors in processing data
  - Bias in background
- Generally need to remove biases somehow to perform assimilation of observation
- For satellite radiances and aircraft temperatures, currently use a procedure within the assimilation itself called Variational Bias Correction (VarBC)

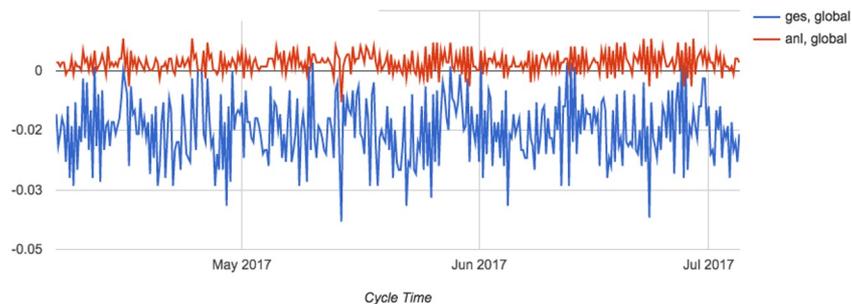
# MetOp-A AMSU-A Ch 6 Mean Departures



Observed-Guess  
Observed-Analysis

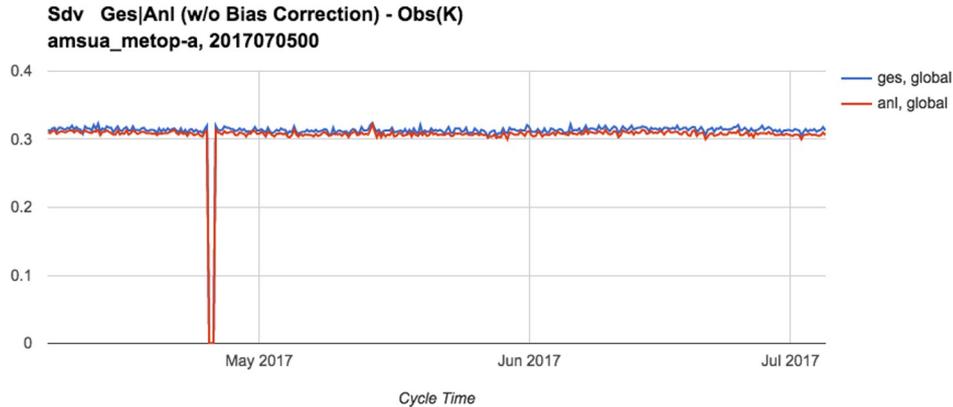
Before  
Bias Correction

After  
Bias Correction



# MetOp-A AMSU-A Ch 6

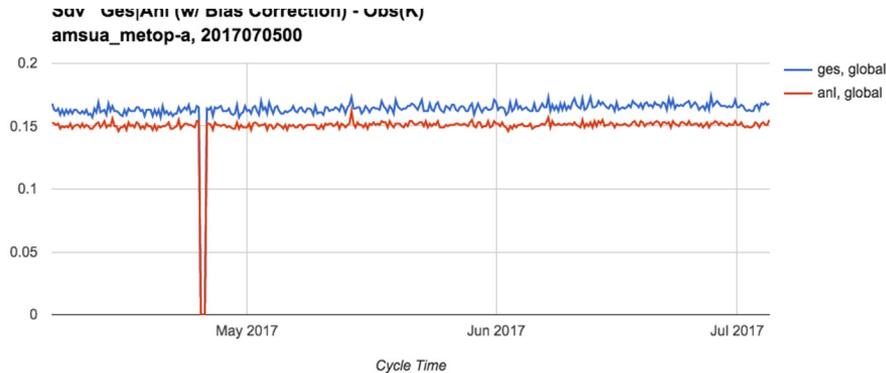
## Std Dev of Departures



Observed-Guess  
Observed-Analysis

Before  
Bias Correction

After  
Bias Correction



# Thinning or Superobbing

- Thinning
  - Reducing spatial or spectral resolution by selecting a reduced set of locations or channels.
  - Can include “intelligent thinning” to use better observation.
- Superobbing
  - Reducing spatial or spectral resolution by combining locations or channels.
  - Can reduce noise.
  - Includes reconstructed radiances.
  - Can include higher moments contained in data [Purser et al., 2010](#).
  - Can be done with obs or departures, but should be done after QC.
- Both can be used to address 3 problems:
  - Redundancy in data.
  - Reduce correlated error.
  - Reduce computational expense.